A Speech Recognition System for Urdu Language

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Abstract-This paper presents a speech processing and recognition system for individually spoken Urdu language words. The speech feature extraction was based on a dataset of 150 different samples collected from 15 different speakers. The data was pre-processed using normalization and by transformation into frequency domain by (discrete Fourier transform). The speech recognition feed-forward neural models were developed in MATLAB. The models exhibited reasonably high training and testing accuracies. Details of MATLAB implementation are included in the paper for use by other researchers in this field. Our ongoing work involves use of linear predictive coding and cepstrum analysis for alternative neural models. Potential applications of the proposed system include telecommunications, multi-media, and voice-activated tele-customer services.

I. INTRODUCTION

Speech processing is a diverse, well-researched topic that finds applications in telecommunication, multi-media and other fields. Speech processing in real-time presents harder challenges than off-line processing. The processing has many facets, for example, distinguishing different utterances, speaker identification, etc.

Sounds are mainly categorized into these groups: voiced sounds (e.g., vowels and nasals), unvoiced sounds (e.g., fricatives), and stop-consonants (e.g., plosives). The speech starts in lungs but is actually formed when the air passes through larynx and vocal tracts [1]. Depending on the status of vocal fold in larynx, the sound can be grouped into: voiced sound that is time-periodic in nature and harmonic in frequency; the unvoiced, which is more noise-like [2].

Speech modeling can be divided into two types of coding: *waveform* and *source* [3]. In the beginning, the researchers tried to mimic the sounds as is, and called

the technique waveform coding. This method tries to retain the original waveform using quantization and redundancy. An alternative approach makes use of breaking the sound up into individual components which are later modeled, separately. This method of utilizing parameters is referred to as source coding.

Different characteristics of speech can used to identify the spoken words, the gender of the speaker, and/or the identity of the speaker. Two important features of speech are *pitch* and *formant frequencies* [4]:

(a) Pitch is a significant distinguishing factor among male and female speakers. The frequency of vibration of vocal folds determines the pitch, for example, 300 times per second oscillation of the folds results in 300 Hz pitch. Harmonics (integer multiples of fundamental frequency) are also created while the air passes through the folds. The age also affects the pitch. Just before puberty, the pitch is around 250 Hz. For adult males, the average pitch is 60 to 120 Hz, and for females, it is 120 to 200 Hz.

(b) The vocal tract, consisting of oral cavity, nasal cavity, velum, epiglottis, and tongue, modulates the pitch harmonics created by the pitch generator. The modulations depend on the diameter and length of the cavities. These reverberations are called formant frequencies (or resonances). The harmonics closer to the formant frequencies get amplified, while others are attenuated.

While the humans are speaking, the formants vary depending on the positions of the tongue, jaw, velum and other parts of the vocal tract. Two related key factors are: bandwidth of each formant, and formant's membership in a known bandwidth. The vowels for all human beings tend to be similar [4].

Each vowel uttered by a person generates different formants. So we can say that the vocal tract is a variable filter whose inputs are (1) the pitch, and (2) the pitch harmonics. The output of the filter is the gain or the attenuation of the harmonics falling in different formant frequencies. The filter is called *variable filter* model. The transfer function for the filter is determined by the formant frequencies [4].

Rabiner and Schafer's [5] discrete-time model make makes use of linear prediction for producing speech. The vocal tract and lip radiation models use discrete excitation signal. An impulse generator emulates voiced speech excitation; the impulses are passed through a glottal shaping filter. The unvoiced speech is generated by a random noise generator.

Ideally, any features selected for a speech model should be (1) not purposely controlled by the speaker, (2) independent of his/her health condition, and (3) tolerant to any environmental/acquisition noise.

Although the pitch can be easily varied by a speaker, the pitch can be easily filtered for any electrical noise, by using a low-pass filter. Formants on the other hand, are unique for different speakers, and are useful in individual speaker identification. In general, a combination of pitch and formant can be used in a speech recognition system.

Many different schemes have been used in the past for speech feature extraction, for example, *discrete Fourier transform (DFT), linear predictive coding (LPC), cepstral analysis,* etc [6]. (In this paper, we only use the DFT technique).

Much research has been on done for English (and other major languages) speech processing/recognition, but application of these time-tested techniques has not been investigated for Urdu language. So we consider ours to be the first effort in developing an Urdu language speech recognition system. In this paper, we provide the system (in the form of MATLAB code) as an *open source* so that other researchers can build up on our current efforts.

II. PRELIMINARIES

A. Overview of Discrete Fourier Transform and its MATLAB Implementation

DFT is itself a sequence rather than a function of continuous variable and it corresponds to equally-spaced frequency samples of discrete time Fourier transform of a signal. Fourier series representation of the periodic sequence corresponds to discrete Fourier transform of finite length sequence. So we can say that DFT is used for transforming discrete time sequence x(n) of finite length into discrete frequency sequence X[k] of finite length [2].

DFT is a function of complex frequency. Usually the data sequence being transformed is real. A waveform is sampled at regular time intervals T to produce the sample sequence of N sample values; n is the sample number, from n=0 to N-1.

$$\{x(nT)\} = x(0), x(T), \dots, x[(N-1)T]$$

For length N input vector X, the DFT is a length-N vector X that has elements:

$$X(k) = \sum_{n=1}^{N} x(n) \cdot e^{-2\pi j \cdot (k-1) \cdot (\frac{n-1}{N})}, \quad k = 1 \dots N$$

The MATLAB function fft(X) calculates the DFT of vector X. Similarly, fft(X, N) calculates N-point FFT, but padded with zeros if X has fewer than N points, and truncated if it has more.

B. Overview of Neural Networks

Neural networks (NNs) have proven to be a powerful tool for solving problems of prediction, classification and pattern recognition [7]-[20]. The NNs are based on the principle of biological neurons. An NN may have one or more input and output neurons as well as one or more hidden layers of neurons interconnecting the input and output neurons. In one of the well-known NN types, the outputs of one layer of neurons send data (only) to the next layer (Figure 1), thus being called feed-forward NNs. *Back-propagation* is a common scheme for creating (training) the NNs. During the process of NN-creation, internal weights $(w_{i,i})$ of the neurons are iteratively adjusted so that the outputs are produced within desired accuracy. The training process requires that the training set (known examples/input-output datasets) be chosen carefully. The selected dataset usually needs to be pre-processed prior to being fed to a NN [21], [22].

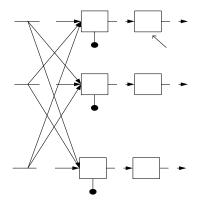


Figure 1. Structure of a simple feed-forward neural network

III. DATA ACQUISITION & PROCESSING

The speech recognition system presented in this model was limited to individual Urdu numerals (0 to 9). The data was acquired by speaking the numerals into a microphone connected to MS-Windows-XP based PC. Fifteen speakers uttered the same number set (0 to 9), specifically, *aik, do, teen, chaar, paanch, shay, saat, aat,* and *nau*. Each sound sample was curtailed to the duration of 50 seconds.

The following data processing steps can be generally used for preparing the data for NN training [25]-[24]:

A. *Pre-processing*: This step may involve logarithmic or some transformation. A normalization may also be needed.

B. *Data length adjustment*: FFT execution time depends on exact number of the samples (N) in the data sequence [xK]. It is desirable to choose the data length equal to a power of two.

C. *Endpoint detection*: This step isolates the word to be detected from the following 'silence'.

(4) *Windowing*: A window is applied to select a smaller time than the complete sample. *Hamming window* is one of the widely used windowing algorithms.

D. *Frame blocking*: Here we make use of the property that the sounds originate from a mechanically slow vocal tract. This assumed stationarity allows overlapping frames of 100ms or so.

E. *Fourier transform*: MATLAB's built-in FFT function provides symmetric data from which the lower half can be used for NN training/testing. Frequency spectrum for numeral *aik* (one) is shown in Figure 2.

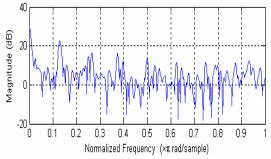


Figure 2. Frequency representation of number *aik* (one)

IV. NEURAL NETWORK TOPOLOGY AND IMPLEMENTATION IN MATLAB

We used single-hidden-layer feed-forward networks in this research. We experimented with many different sizes of the hidden layer, i.e., 5 to 20 neurons. In most cases, the training accuracy flattened out with hidden-layer count of 10. The training iterations (*epochs*), however, did reduce with higher number of hidden layer neurons. The NN used 64 FFT magnitudes as inputs, and produced ten separate predictions (one for each number). This means that we had 64 neurons in the input layer, and 10 neurons in the output layer.

From the overall dataset of 150 speech samples (10 numbers spoken by 15 different speakers), we used 90% as the *training set*, and set aside the remaining 10% as *validation/testing set*. The learning rate of 0.01, and the training error tolerance of 0.01 were used. Epoch count was limited to 5000.

Now, we provide details of NN implementation using MATLAB. A feed-forward N-layer NN is created by *newff* MATLAB command [25]:

net = newff(PR,[S1, S2, ..., SN1],{TF1
TF2...TFN1},BTF,BLF,PF)

where

- PR = Rx2 matrix of min and max values for R input elements
- S1 = Size of ith layer, for NI layers
- TFi = Transfer function of ith layer. (Default = 'tansig')
- BTF = Backprop network training function. (Default = 'trainlm')
- BLF = Backprop weight/bias learning function. (Default = 'learngd')
- PF = Performance function (default = 'mse')

The NN is created and trained with the following set of MATLAB commands:

```
% p[] = array of training inputs
% t[] = array of targets/outputs
% minmax_of_p = array containing
% mins and maxs of p[]
% network configuration
S1 = 10; % layer-1 neurons
S2 = 10; % layer-2 neurons
net = []; % network reset
% two-layer network declaration
net = newff(minmax_of_p,[S1, S2],
{'tansig','purelin'},'traingd');
```

```
% training and display parameters
net.trainParam.show = 50;
net.trainParam.lr = 0.01;% lrn rate
net.trainParam.goal = 0.01; % trg tol
net.trainParam.epochs = 5000;
```

```
% finally the training happens with:
net = train(net,p,t);
```

The effect of learning rate (LR) on training is shown in Figures 3 and 4. In our experiments, a larger value of LR (0.05) took longer to train (Figure 3) as compared to the LR of 0.01 (Figure 4), although in both cases, the NNs were able to meet the maximum prediction error criterion of 0.01.

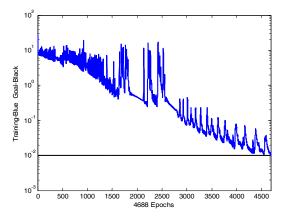


Figure 3. Training epochs and error (LR=0.05)

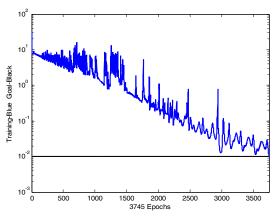


Figure 4. Training epochs and error (LR=0.01)

V. CONCLUSIONS & FUTURE WORK

Ours is the first known attempt at using an NN to recognize spoken Urdu language words (numbers, in this case). The DFT of the acquired data was used for training and testing the speech recognition NN. The network made predictions with high accuracy. Currently, we are investigating use of LPC and cepstrum analysis for the same purpose. Our ultimate goal is to implement the Urdu speech recognition in hardware, for example, a DSP chip. The proposed system can be used in applications such as multi-media, telecommunications, and voice-driven customer service, in countries such as Pakistan and India.

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